## Stat 534: formulae referenced in lecture, week 5, part 2: Overparameterized models and models accounting for individual heterogeneity Corrected, 30 Sept 21

Mtb: both behavioural response and time-dependent capture probabilities

- Our first encounter with an overparameterized mark-recapture model
- For 3 occasions: 6 parameters, 3 p's, 2 c's (no  $c_1$ ) and 1 N
- Let's work out the capture probabilities

Time				
1	2	3	# animals	probability
Y	Υ	Υ	$n_{111}$	$p_1 c_2 c_3$
Υ	Υ	Ν	$n_{110}$	$p_1 c_2 (1 - c_3)$
Υ	Ν	Υ	$n_{101}$	$p_1(1-c_2)c_3$
Υ	Ν	Ν	$n_{100}$	$p_1(1-c_2)(1-c_3)$
Ν	Υ	Υ	$n_{011}$	$(1-p_1)p_2c_3$
Ν	Υ	Ν	$n_{010}$	$(1-p_1)p_2(1-c_3)$
Ν	Ν	Υ	$n_{001}$	$(1-p_1)(1-p_2)p_3$
Ν	Ν	Ν	$n_{000}$	$(1-p_1)(1-p_2)(1-p_3)$

- Nothing looks amiss here, so let's count sufficient statistics
- based on the patterns for Mt and Mb, you would expect:
  - $-n_i$ : number caught at time i
  - $-m_i$ : number marked caught at time i
  - $M_{t+1}$ : total number of unique individuals seen
- Looks like 6 sufficient statistics, enough to estimate 6 parameters
- But:  $M_{t+1}$  is not "new" information. It can be computed from  $n_i$  and  $m_i$ 
  - # 1st seen at time 1 + # first seen at time 2 + # first seen at time 3 - =  $n_1 + (n_2 - m_2) + (n_3 - m_3)$
- so no unique solution! Many sets of parameters have the same lnL
- Sometimes can spot redundancy by examining the capture history probabilities
- Have a problem when two parameters only appear multiplied or added together, e.g.  $\theta_1 \theta_2$  or  $\theta_1 + \theta_2$
- Numerical assessments:

- look at the rank of the negative Hessian matrix (= # non-zero eigenvalues)
- often, use very small (e.g., < 0.005) because of numerical issues computing the Hessian
- For one particular data set, the eigenvalues were:
  44.1339 25.0000 20.8004 18.6077 0.0022 0.0015
  Two parameters have very large variances, so can not be identified
- or look for massive standard errors for one or more parameters

Solutions for overparameterized models:

- Simplify the model, e.g. reparameterize  $\theta_1 \theta_2$  as a single parameter
- Put constraints on the parameters
- E.g., for Mtb you could:
  - Make time effects follow a logistic regression

logit 
$$p_i = \log\left(\frac{p_i}{1-p_i}\right) = \beta_0 + \beta_1 i$$

- Connect recapture and capture probabilities, also usually by a logistic

logit 
$$c_i = \nu + \text{logit } p_i$$

Model Mh: allows each of the N individuals to have a different  $p_i$ 

m.

• The capture history for five **individuals**:

Time					
	1	2	3	# animals	probability
	Υ	Υ	Υ	1	$p_1^3$
	Υ	Υ	Υ	1	$p_2^3$
	Υ	Υ	Ν	1	$p_3^2(1-p_3)$
	Ν	Ν	Ν	1	$(1-p_4)^3$
	Ν	Ν	Ν	1	$(1-p_5)^3$

- Sufficient statistics are the # captures and # missed for each of the  $M_{t+1}$  animals seen at least once
- There are  $M_{t+1}$  sufficient statistics, but N+1 parameters
- Can't estimate N without modeling  $p_i$  or using a completely different approach (coverage)

Modeling  $p_i$  using a Beta(a,b) distribution

- $f(p|a,b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} p^{a-1} (1-p)^{b-1}$ 
  - $-\Gamma(x)$  is the gamma function
  - Uniform(0,1) is Beta(1,1)
  - Hand drawn pictures
  - Key is that all are unimodal except when peaks are at 0 or 1
- mean:  $\mu_p = \mathbf{E} \ p = \frac{a}{a+b}$
- variance: Var  $p = \frac{ab}{(a+b)^2(a+b+1)} = \mu_p (1-\mu_p) \frac{1}{a+b+1}$
- The approach:
  - Estimate a and b from the capture histories of the  $M_{t+1}$  observed individuals
  - Assume all N individuals have capture probabilities from that Beta(a, b) distribution
  - Provides sufficient information to estimate N
- Ken Burnham worked on this model extensively in the 1980's
- Great idea in theory, didn't work in practice
- Problem is that capture probabilities are more complicated than can be modeled by a Beta distribution

Pledger heterogeneity models (2000)

- For now, focus on Mh: no time or behavioural effects
- $p_i$  = probability individual *i* is captured on an occasion
- P[capture history  $| p_i ] = P[capture history | p_i] = \prod_{j=1}^t p_i^{X_{ij}} (1-p_i)^{(1-X_{ij})}$
- If don't know  $p_i$ , then want the marginal probability

$$P[\text{capture history}] = \int_{p_i=0}^{1} f(\text{capture history} \mid p_i) f(p_i) d p_i$$

- Burnham's beta model used this idea with a beta distribution for  $f(p_i)$ 
  - beta and binomial distributions "play nicely" together
  - the integral has a analytical solution
- Shirley Pledger proposed a more flexible distribution for  $f(p_i)$

• finite mixture model:  $p_i$  has one of two values (could be 3 or more but 2 often sufficient)

$$f(p_i) = \begin{cases} \pi_1 & \text{with probability } f_1 \\ \pi_2 & \text{with probability } f_2 = 1 - f_1 \end{cases}$$

• So, the marginal distribution is a sum, not an integral, because  $p_i$  has only 2 values:

$$P[\text{capture history}] = \sum_{a=1}^{2} f_a P[\text{capture history}|p_a]$$

- for 2 components: 3 parameters for capture probability:  $f_1$ ,  $\pi_1$ ,  $\pi_2$ .
  - More parameters if more than 2 mixture components,
  - e.g., for 3 components:  $f_1$ ,  $f_2$ ,  $\pi_1$ ,  $\pi_2$ ,  $\pi_3$
- Likelihood is (for 2 components):

$$L(N, f_a, \pi_1, \pi_2 \mid \{X_{ij}\}) = \frac{N!}{\text{constant} \times (N - M_{t+1})!} \prod_{i=1}^N \left[\sum_{a=1}^2 f_a \text{ P[capture history}|p_a]\right]$$

- lnL is not simple includes log sum(stuff)
- Can generalize to include time and behavioural effects

Huggins model: relate  $p_i$  to one or more covariates,  $X_i$ 

• Logistic regression model: logit $(p_i) = \log \frac{p_i}{1-p_i} = \beta_0 + \beta_1 X_i$ 

$$p_i = \frac{1}{1 + e^{-(\beta_0 + \beta_1 X_i)}}$$

- Not fit using the "usual" logistic regression algorithms
  - Only have data for individuals seen at least once missing many of the 0's
  - Need to model P[capture history | captured at least once]

 $P[capture history | captured at least once] = \frac{P[(capture history) \& (captured at least once)]}{P[captured at least once]}$ 

- P[capture history and captured at least once] = product of appropriate p or p and c terms (usual expression)
- Define  $p_{ij} = P[\text{capture individual } i \text{ on occasion } j]$
- P[captured at least once] = 1 P[never captured] =  $1 \prod_{j=1}^{k} (1 p_{ij})$

- Huggins incorporated time and behavioural responses by adding
  - a unique value for each time
  - First captures: note time-specific intercept

logit 
$$p_{ij} = \beta_{0j} + \beta_1 X_i$$

- -c (recapture probs) have a fixed relationship to p (first capture probs)
- Recaptures: the  $p_{ij}$  model + a consistent trap-happy or trap-shy effect,  $\nu$

logit  $c_{ij} = \nu + \beta_{0j} + \beta_1 X_i = \nu + \text{logit } p_{ij}$ 

- Provides a simple way to model c and p
- What about estimating N?
  - N not in the likelihood
  - need some other way to estimate it

Huggins model: estimating N

- Add up 1/P[seen at least once] for each observed animal
- (Horvitz-Thompson estimator: Population Total  $Y = \sum_{i=1}^{n} Y_i / \pi_i$ )

$$\widehat{N} = \sum_{i=1}^{M_{t+1}} \frac{1}{1 - \prod_{j=1}^{t} (1 - \hat{p}_{ij})}$$

• Can get a variance estimator (complicated, not illuminating)

Is Huggins  $\hat{N}$  a reasonable estimator?

- Prefer unbiased estimates.
  - $\hat{N}$  is a random variable.
  - Would like E $\hat{N}=N$
  - i.e., sometimes  $\hat{N}$  is too high, sometimes too low, but on average spot on
- Is  $\hat{N}_{Huggins}$  unbiased?
  - Yes, if  $p_{ij}$  is known precisely
  - Define  $p_i(\theta) = P[\text{individual } i \text{ captured at least once } | \text{ parameters } \theta]$
  - Define  $C_i = \begin{cases} 0 & \text{when individual not captured} \\ 1 & \text{when individual was captured} \end{cases}$

$$E \ \hat{N}_{Huggins} = E \sum_{i=1}^{M_{t+1}} \frac{1}{p_i(\theta)} = E \sum_{i=1}^{N} \frac{C_i}{p_i(\theta)} = \sum_{i=1}^{N} \frac{E \ C_i}{p_i(\theta)} = \sum_{i=1}^{N} \frac{p_i(\theta)}{p_i(\theta)} = N$$

- 3rd step requires known  $p_i(\theta)$
- In practice,  $p_i(\theta)$  is estimated, because coefficients in the models for  $p_{ij}$  and  $c_{ij}$  are estimated
- bias is small so long as sufficient data to provide good estimates of  $p_i(\theta)$

Sample Coverage (Chao heterogeneity estimators)

• Coverage: proportion of total capture probability associated with observed individuals

$$C = \sum_{i=1}^{M_{t+1}} \frac{p_i \operatorname{I}(\text{seen at least once})}{\sum_{i=1}^{N} p_i}$$

- Explanation / example in hand-written notes
- Notation:
  - $\overline{p}$  mean capture probability in the population
  - $\gamma$   $\,$  c.v. of capture probabilities in the population
  - n total # captures
  - $f_i \quad \#$  number of individuals seen i times, e.g.:
  - $f_1 \#$  number seen only once
  - $f_2 \#$  number seen twice, etc.
- Assume a particular model for the data (details in Chao & Lee 1992, 1994, not important)

use to derive expected values

$$\frac{\mathbf{E}\ M_{t+1}}{\mathbf{E}\ C} \cong N - \frac{n\ (1-\overline{p})^{n-1}}{\mathbf{E}\ C} \gamma^2$$

- Need to estimate C,  $\overline{p}$ , and  $\gamma$
- <u>p</u>:
- Have  $p_i$  for observed individuals, but average is biased
- More likely to observe individuals with large  $p_i$
- $-\overline{p}$  in the population can be estimated from  $f_1$ : # individuals seen only once

$$N \cong \frac{\mathbf{E} \ M_{t+1}}{\mathbf{E} \ C} + \frac{\mathbf{E} \ f_1}{\mathbf{E} \ C} \gamma^2$$

- $\gamma$ : sample cv not so obviously biased
- C: an old estimator, from the 1950's

$$\hat{C} = 1 - \frac{f_1}{\sum_{i=1} ti f_i}$$

- There is a bias corrected estimate, but really want unbiased estimates of  $1/\hat{C}$  and  $\gamma^2/\hat{C}$
- Putting the pieces together: applying the "plug-in" principle

$$\hat{N} = \frac{M_{t+1}}{\hat{C}} + \frac{f_1}{\hat{C}}\hat{\gamma}^2$$