Stat 534: formulae referenced in lecture, week 5, part 2: Overparameterized models and models accounting for individual heterogeneity Corrected, 30 Sept 21

Mtb: both behavioural response and time-dependent capture probabilities

- Our first encounter with an overparameterized mark-recapture model
- For 3 occasions: 6 parameters, 3 p 's, 2 c 's (no c_1) and 1 N
- Let's work out the capture probabilities

- Nothing looks amiss here, so let's count sufficient statistics
- based on the patterns for Mt and Mb, you would expect:
	- n_i : number caught at time i
	- m_i : number marked caught at time i
	- M_{t+1} : total number of unique individuals seen
- Looks like 6 sufficient statistics, enough to estimate 6 parameters
- But: M_{t+1} is not "new" information. It can be computed from n_i and m_i
	- $\#$ 1st seen at time 1 + $\#$ first seen at time 2 + $\#$ first seen at time 3 $- = n_1 + (n_2 - m_2) + (n_3 - m_3)$

$$
= n_1 + (n_2 - m_2) + (n_3 - m_3)
$$

- so no unique solution! Many sets of parameters have the same lnL
- Sometimes can spot redundancy by examining the capture history probabilities
- Have a problem when two parameters only appear multiplied or added together, e.g. $\theta_1\theta_2$ or $\theta_1 + \theta_2$
- Numerical assessments:
- look at the rank of the negative Hessian matrix $(=\# \text{ non-zero eigenvalues})$
- often, use very small (e.g., < 0.005) because of numerical issues computing the Hessian
- For one particular data set, the eigenvalues were: 44.1339 25.0000 20.8004 18.6077 0.0022 0.0015 Two parameters have very large variances, so can not be identified
- or look for massive standard errors for one or more parameters

Solutions for overparameterized models:

- Simplify the model, e.g. reparameterize $\theta_1 \theta_2$ as a single parameter
- Put constraints on the parameters
- E.g., for Mtb you could:
	- Make time effects follow a logistic regression

$$
logit p_i = log\left(\frac{p_i}{1 - p_i}\right) = \beta_0 + \beta_1 i
$$

– Connect recapture and capture probabilities, also usually by a logistic

$$
logit c_i = \nu + logit p_i
$$

Model Mh: allows each of the N individuals to have a different p_i

• The capture history for five **individuals**:

- Sufficient statistics are the $\#$ captures and $\#$ missed for each of the M_{t+1} animals seen at least once
- There are M_{t+1} sufficient statistics, but N+1 parameters
- Can't estimate N without modeling p_i or using a completely different approach (coverage)

Modeling p_i using a Beta(a,b) distribution

- $f(p|a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} p^{a-1} (1-p)^{b-1}$
	- $\Gamma(x)$ is the gamma function
	- Uniform $(0,1)$ is Beta $(1,1)$
	- Hand drawn pictures
	- Key is that all are unimodal except when peaks are at 0 or 1
- mean: $\mu_p = E p = \frac{a}{a+1}$ $_{a+b}$
- variance: Var $p = \frac{ab}{(a+b)^2(a)}$ $\frac{ab}{(a+b)^2(a+b+1)} = \mu_p(1-\mu_p)\frac{1}{a+b}$ $a+b+1$
- The approach:
	- Estimate a and b from the capture histories of the M_{t+1} observed individuals
	- Assume all N individuals have capture probabilities from that $Beta(a, b)$ distribution
	- Provides sufficient information to estimate N
- Ken Burnham worked on this model extensively in the 1980's
- Great idea in theory, didn't work in practice
- Problem is that capture probabilities are more complicated than can be modeled by a Beta distribution

Pledger heterogeneity models (2000)

- For now, focus on Mh: no time or behavioural effects
- p_i = probability individual *i* is captured on an occasion
- P[capture history $|p_i] = P$ [capture history $|p_i] = \prod_{j=1}^{t} p_i^{X_{ij}}$ $\int_i^{X_{ij}} (1-p_i)^{(1-X_{ij})}$
- If don't know p_i , then want the marginal probability

P[capture history] =
$$
\int_{p_i=0}^{1} f(capture history | p_i) f(p_i) d p_i
$$

- Burnham's beta model used this idea with a beta distribution for $f(p_i)$
	- beta and binomial distributions "play nicely" together
	- the integral has a analytical solution
- Shirley Pledger proposed a more flexible distribution for $f(p_i)$

• finite mixture model: p_i has one of two values (could be 3 or more but 2 often sufficient)

$$
f(p_i) = \begin{cases} \pi_1 & \text{with probability } f_1 \\ \pi_2 & \text{with probability } f_2 = 1 - f_1 \end{cases}
$$

• So, the marginal distribution is a sum, not an integral, because p_i has only 2 values:

$$
P[{\rm capture\ history}] = \sum_{a=1}^{2} f_a \ P[{\rm capture\ history}] p_a]
$$

- for 2 components: 3 parameters for capture probability: f_1 , π_1 , π_2 .
	- More parameters if more than 2 mixture components,
	- e.g., for 3 components: $f_1, f_2, \pi_1, \pi_2, \pi_3$
- Likelihood is (for 2 components):

$$
L(N, f_a, \pi_1, \pi_2 \mid \{X_{ij}\}) = \frac{N!}{\text{constant} \times (N - M_{t+1})!} \prod_{i=1}^N \left[\sum_{a=1}^2 f_a \text{ P}[\text{capture history}|p_a] \right]
$$

- lnL is not simple includes log sum(stuff)
- Can generalize to include time and behavioural effects

Huggins model: relate p_i to one or more covariates, X_i

• Logistic regression model: $logit(p_i) = log \frac{p_i}{1-p_i} = \beta_0 + \beta_1 X_i$

$$
p_i = \frac{1}{1 + e^{-(\beta_0 + \beta_1 X_i)}}
$$

- Not fit using the "usual" logistic regression algorithms
	- Only have data for individuals seen at least once missing many of the 0's
	- Need to model P[capture history | captured at least once]

 $P[\text{capture history} \mid \text{ captured at least once}] = \frac{P[(\text{capture history}) \& (\text{captured at least once})]}{P[\text{output to the other circle}]}$ P[captured at least once]

- P[capture history and captured at least once] = product of appropriate p or p and c terms (usual expression)
- Define $p_{ij} = P$ [capture individual i on occasion j]
- P[captured at least once] = 1 P[never captured] = $1 \prod_{j=1}^{k} (1 p_{ij})$
- Huggins incorporated time and behavioural responses by adding
	- a unique value for each time
	- First captures: note time-specific intercept

$$
logit p_{ij} = \beta_{0j} + \beta_1 X_i
$$

- c (recapture probs) have a fixed relationship to p (first capture probs)
- Recaptures: the p_{ij} model + a consistent trap-happy or trap-shy effect, ν

logit $c_{ij} = \nu + \beta_{0j} + \beta_1 X_i = \nu + \text{logit } p_{ij}$

- Provides a simple way to model c and p
- What about estimating N ?
	- N not in the likelihood
	- need some other way to estimate it

Huggins model: estimating N

- Add up $1/P$ [seen at least once] for each observed animal
- (Horvitz-Thompson estimator: Population Total $Y = \sum_{i=1}^{n} Y_i/\pi_i$)

$$
\widehat{N} = \sum_{i=1}^{M_{t+1}} \frac{1}{1 - \prod_{j=1}^{t} (1 - \hat{p}_{ij})}
$$

• Can get a variance estimator (complicated, not illuminating)

Is Huggins \hat{N} a reasonable estimator?

- Prefer unbiased estimates.
	- \hat{N} is a random variable.
	- Would like E $\hat{N} = N$
	- i.e., sometimes \hat{N} is too high, sometimes too low, but on average spot on
- Is $\hat{N}_{Hugging}$ unbiased?
	- Yes, if p_{ij} is known precisely
	- Define $p_i(\theta) = P$ [individual *i* captured at least once | parameters θ]
	- $-$ Define $C_i =$ (0 when individual not captured 1 when individual was captured

$$
\text{E }\hat{N}_{Huggins} = E \sum_{i=1}^{M_{t+1}} \frac{1}{p_i(\theta)} = E \sum_{i=1}^{N} \frac{C_i}{p_i(\theta)} = \sum_{i=1}^{N} \frac{E C_i}{p_i(\theta)} = \sum_{i=1}^{N} \frac{p_i(\theta)}{p_i(\theta)} = N
$$

- 3rd step requires known $p_i(\theta)$
- In practice, $p_i(\theta)$ is estimated, because coefficients in the models for p_{ij} and c_{ij} are estimated
- bias is small so long as sufficient data to provide good estimates of $p_i(\theta)$

Sample Coverage (Chao heterogeneity estimators)

• Coverage: proportion of total capture probability associated with observed individuals

$$
C = \sum_{i=1}^{M_{t+1}} \frac{p_i \operatorname{I}(\text{seen at least once})}{\sum_{i=1}^{N} p_i}
$$

- Explanation / example in hand-written notes
- Notation:
	- \bar{p} mean capture probability in the population
	- γ c.v. of capture probabilities in the population
	- n total $\#$ captures
	- f_i # number of individuals seen i times, e.g.:
	- f_1 # number seen only once
	- f_2 # number seen twice, etc.
- Assume a particular model for the data (details in Chao & Lee 1992, 1994, not important)

use to derive expected values

$$
\frac{\mathrm{E} N_{t+1}}{\mathrm{E} C} \cong N - \frac{n (1 - \overline{p})^{n-1}}{\mathrm{E} C} \gamma^2
$$

- Need to estimate C, \bar{p} , and γ
- \bullet \overline{p} :
- $-$ Have p_i for observed individuals, but average is biased
- More likely to observe individuals with large p_i
- $-\bar{p}$ in the population can be estimated from f_1 : # individuals seen only once

$$
N \cong \frac{\operatorname{E} M_{t+1}}{\operatorname{E} C} + \frac{\operatorname{E} f_1}{\operatorname{E} C} \gamma^2
$$

- γ : sample cv not so obviously biased
- C: an old estimator, from the 1950's

$$
\hat{C} = 1 - \frac{f_1}{\sum_{i=1}^{i} t_i f_i}
$$

- There is a bias corrected estimate, but really want unbiased estimates of $1/\hat{C}$ and γ^2/\hat{C}
- $\bullet~$ Putting the pieces together: applying the "plug-in" principle

$$
\hat{N} = \frac{M_{t+1}}{\hat{C}} + \frac{f_1}{\hat{C}}\hat{\gamma}^2
$$